|  |  |  |  |
| --- | --- | --- | --- |
| **Name** | Jenny Reiman | Jason Laqua | Andrew Kirkham |
| **Hours** | 7 | 6 | 5 |
| **Reading** | Vex quickstart, networking, IDE guide | Vex binder | N/A |
| **Tasks Completed** | Hello World Robot | Build Robot | Hello World Android |
| **Tasks for next week** | Drive robot forward/back, turn left/right | 10% Grade | Remote Control Using Vex Radio, Obstacle Avoidance |

**Open issues:** Drive Robot, 10% Grade, Remote control with vex radio, obstacle avoidance

**Anything else:**

|  |  |  |  |
| --- | --- | --- | --- |
| What | Who | When | Done |
| Hello World Robot | Jenny | 5-Sep | ✓ |
| Hello World Android | Andrew | 5-Sep | ✓ |
| Build drivetrain | Jason | 5-Sep | ✓ |
| Attach motors | Jason | 5-Sep | ✓ |
| Mount Vex to structure | Jason | 5-Sep | ✓ |
| Plug in motors | Jason | 5-Sep | ✓ |
| Remote Control Using Vex Radio | Andrew | 12-Sep |  |
| Robot goes forward/backwards/left/right | Jenny | 12-Sep |  |
| Obstacle Avoidance | Andrew | 12-Sep |  |
| 10% Grade | Jason | 12-Sep |  |
| Robot/Android not damaged | All | 19-Sep |  |
| Communication Android to Android | All | 19-Sep |  |
| Communication Android to Vex | All | 19-Sep |  |
| Vex Remote emergency stop | Jenny | 19-Sep |  |
| Setting up Ad Hoc Network | Jason | 19-Sep |  |
| Android Remote emergency stop | Andrew | 19-Sep |  |
| Send a command | Jenny | 19-Sep |  |
| Receive a Command on android | Andrew | 19-Sep |  |
| Receive a Command on vex | Jason | 19-Sep |  |
| Connect Android to Android | Andrew | 19-Sep |  |
| Connect Android to vex | Jenny | 19-Sep |  |